

Techman Robot × Vacuum Gripper



Check out the application video

VRG Related Video : <https://www.pisco.co.jp/en/product/r/r08/#product-video>

VMG Related Video : <https://www.pisco.co.jp/en/product/r/r10/#product-video>

■ Characteristics of rectangular ring type VRG and general-purpose type VMG

- ☐ Vacuum grippers suitable for lifting large workpieces.
- ☐ Built-in high flow vacuum generator.

Max. suction flow: 760 l/min (For models with 3 built-in ejectors).

Large Flow Vacuum Generator Specifications

Rated supply pressure (MPa)	0.5								
Final vacuum (kPa)	-94								
Suction flow (ℓ/min)	290	Saved approx. 62%	Approx. 2.6 times	550	Saved approx. 60%	Approx. 2.5 times	76	Saved approx. 57%	Approx. 2.3 times
Air consumption (ℓ/min)	110			220			330		
No. of nozzles (pcs)	1			2			3		

Air consumption is **saved up to 62%** relative to suction flow.

**Air
Saving**

Suction flow rate is up to 2.6 times the air consumption.

Large Flow

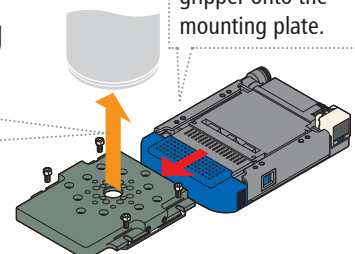
Capable of lifting even porous workpieces.

- External vacuum pump compatible type is also available.
 - Can be easily installed by sliding it onto the flange mounting plate once the plate has been fixed to the robot.
- Improved operability and safety.**
- ① Fix the mounting

① Fix the mounting plate to the robot.

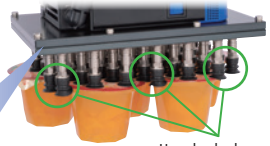
P.C.D. 50

② Slide the vacuum gripper onto the mounting plate.



Three types of suction surfaces

Two sponge types (rectangular ring type and whole surface type) and aligned vacuum pads type.

Type	Rectangular ring type / VRG		General-purpose type / VMG	
	Sponge Theoretical max. suction force 1512.7 N (※1)		Sponge (Whole surface) Theoretical max. suction force 1546.4 N (※1)	
Recommended workpieces	Aligned vacuum pads Theoretical max. suction force 2369.5 N (※1)			
	Large bags such as multiwall bags Shrink-wrapped plastic bottles  Supple sponge pad conforms to and lifts uneven or deformed surfaces of workpieces.		Uneven workpieces, such as wood and exterior wall decoration materials 	
Pad replacement	Cardboard boxes and bagged items 		Replaceable by replacing the VRG sponge plate.	
	Replaceable by replacing the VMG sponge plate.		Vacuum pad + pad screw set (pad connection configuration code: M6) can be mounted. (※2)	
Accessories	Spacer (included) The stroke can be adjusted to suit the workpiece by changing the height of the adjusting plate on the inside of the pad. Four suction strokes in total: 10, 15, 20, and 25 mm (factory setting: 25 mm). Adjustable in 5 mm increments. * For VRG1515: 8, 13, 18, and 23 mm (factory setting: 23mm).		◀ VMG common plate is available for easy pad/sponge switching ▶	
	Fixed orifice (optional) Suppresses vacuum degradation due to leakage from non-absorbed areas by attaching an orifice to regulate the flow rate. The orifice coupling type makes it easy to attach/detach the pads. The pads unnecessary for suction can be removed thanks to the socket's built-in shutoff valve.		Fixed orifice or orifice coupling (optional)  Un-adsorbed areas	

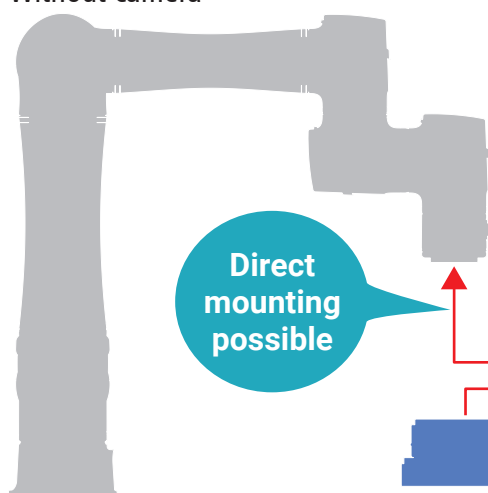
Capable of lifting even if there are un-adsorbed areas.

※1. Safety factor 1/4 considered.

※2. Bellows-type vacuum pads are provided as standard. If other pads are to be installed, order "No pad". (Vacuum pads are sold separately.)

Easy to install on Techman robot.

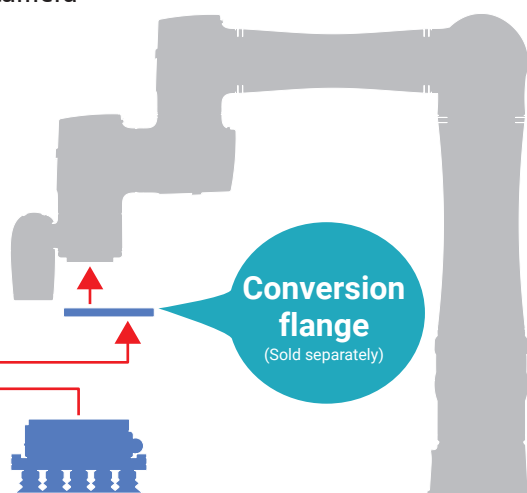
Without camera



VRG

Rectangular ring type

With camera



VMG

Whole surface type

Aligned vacuum pads type

Can be **installed directly to the robot flange**.
No adapter plate required.

Adjust the installation position of the vacuum gripper using the **Conversion flange** (sold separately) to ensure that **the camera is not obstructed**.

※ Available for Vacuum gripper type : VRG1515, VRG2817 and VMG2618

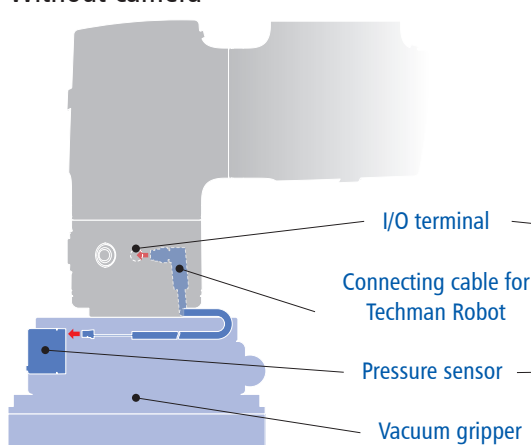


Model code : **VMG-RFA-D50**

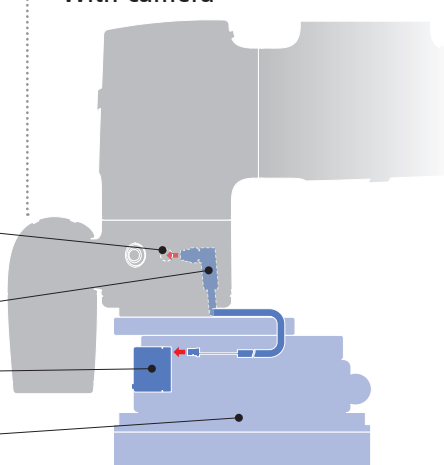
Connecting cable for tool end I/O terminal is available. (Sold separately)

Connecting cable to connect the pressure sensor that comes standard with the vacuum gripper to the I/O terminal on the end of the Techman Robot.

Without camera



With camera



Model code : **VMG-SC-C35-TM**

(Cable length : 350 mm)

※ If you need a cable length other than the above, please contact us.

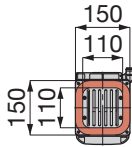
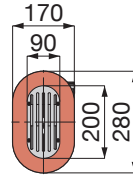
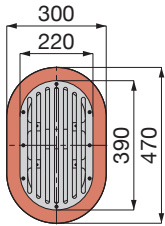


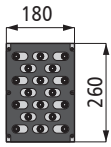
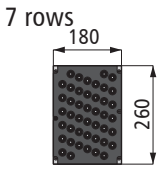
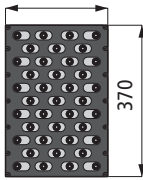
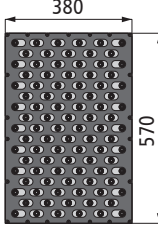
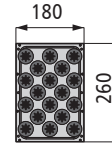
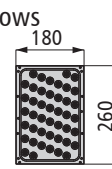
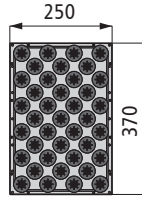
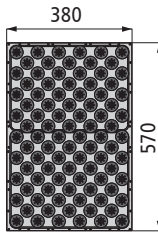
Connection example



Model code when both conversion flange and connecting cable are required for camera-equipped type : **VMG-RFA-SC-SET-TM**

Vacuum gripper shape / Size list

Type		Rectangular ring type (sponge) / VRG		
Pad O.D. size code		1515	2817	4730
Size (mm)				
Applicable techman robot	Without camera	✓	✓	✓
	With camera	✓	✓	×
Fluid medium		Air, Vacuum (※1)		
Operating pressure range	Only for vacuum generator spec.	0.3~0.7 MPa		
Rated supply pressure		0.5 MPa		
Noise level		70 dB (A)		
Operating vacuum pressure		-100~0 kPa (Only for External Vacuum Pump spec)		
Operating temp. range		5~50 °C (No freezing)		
Theoretical suction force (※2, ※3)	FoS 1/4 (Horizontal lifting)	235.8 N	326.2 N	1512.7 N
	FoS 1/8 (Vertical lifting)	117.9 N	163.1 N	756.4 N

Type		General-purpose type / VMG					
		Sponge (whole surface type)			Aligned vacuum pads type		
Plate size code		2618	3725	5738	2618	3725	5738
Size (mm)		5 rows  7 rows 	7 rows 	11 rows 	5 rows  7 rows 	7 rows 	11 rows 
Applicable techman robot	Without camera	✓	✓	✓	✓	✓	✓
	With camera	✓	×	×	✓	×	×
Fluid medium		Air, Vacuum (※1)					
Operating pressure range	Only for vacuum generator spec.	0.3~0.7 MPa					
Rated supply pressure		0.5 MPa					
Noise level		70 dB (A)					
Operating vacuum pressure		-100~0 kPa (Only for External Vacuum Pump spec)					
Operating temp. range		5~50°C (No freezing)					
Theoretical suction force (※2, ※3)	FoS 1/4 (Horizontal lifting)	296.1 N (5 rows) 277.3 N (7 rows)	641.6 N	1546.4 N	453.7 N (5 rows) 277.3 N (7 rows)	983.1 N	2369.5 N
	FoS 1/8 (Vertical lifting)	148.1 N (5 rows) 138.6 N (7 rows)	320.8 N	773.2 N	226.9 N (5 rows) 138.6 N (7 rows)	491.5 N	1184.7 N

※1) "Fluid medium: vacuum" is only for external vacuum pump spec.

※2) Theoretical suction force at a vacuum of -80 kPa.

※3) Do not exceed the maximum load capacity of 980N of the main body mounting section, including the weight of the gripper body and inertia forces during transport.

